

2. TEST CASES GENERATION IN ECAT

Four test cases generation techniques are equipped to *eCAT*: *Goal-oriented*, *Ontology-based*, *Random*, and *Evolutionary mutation* (also called evol-mutation).

GOAL-ORIENTED. Goal-oriented test cases generation is a part of a methodology presented in [6] that integrates testing into *Tropos*, providing a systematic way of deriving test cases from *Tropos* output artifacts. *eCAT* can take these artifacts as inputs to generate test case skeletons that are aimed at testing goal fulfillment. Specific test inputs (i.e. message content), and expected outcome are partially generated from plan design (e.g. UML activity or sequence diagrams) and are then completed manually by testers.

ONTOLOGY-BASED. Agent behaviors are often influenced by messages received. Hence, at the core of test case generation is the ability to build meaningful messages that exercise the agent under test so as to cover most of the possible running conditions. *eCAT* can take advantage of agent interaction ontologies, which define the semantics of agent interactions, in order to automatically generate both valid and invalid test inputs, to provide guidance in the exploration of the input space, and to obtain a test oracle against which to validate the test outputs [7].

RANDOM. *eCAT* is capable of generating random test cases, following the random test data generation strategy [4]. First, the *Autonomous Tester Agent* selects a communication protocol among those provided by the agents platform, e.g. FIPA Interaction Protocol [2]. Then, messages are randomly generated and sent to the agents under test. The message format is that prescribed by the agent environment of choice (such as the FIPA ACLMessage [3]), while the content is constrained by a domain data model. Such a model prescribes the range and the structure of the data that are produced randomly, either in terms of generation rules or in the (simpler) form of sets of admissible data that are sampled randomly.

EVOL-MUTATION. This technique combines mutation [1] and evolutionary [9] testing for the automated generation of the test cases executed by the tester agent in a given multi-agent environment. Intuitively, we use the mutation adequacy score as a fitness measure to guide evolution, under the hypothesis that test cases that are better at killing mutants are also likely to be better at revealing real faults. The proposed technique consists of the following three steps:

Step 0: Preparation, given the MAS under test M , we apply mutation operators to M to produce a set of mutants $\{M_1, M_2, \dots, M_n\}$. One or more operators are applied to one or more (randomly chosen) agents in M .

Step 1: Test execution and adequacy measurement, the *Autonomous Tester Agent* executes the test cases $\{TC_1, TC_2, \dots, TC_n\}$ on all the mutants. Initially, test cases are those derived from goal analysis by the user. The *Autonomous Tester Agent* then computes the adequacy of each test case (fitness value): $F(TC_i) = \frac{K_i}{N}$, where K_i is the number of mutants killed by TC_i . To increase performance, the executions of the test cases on the mutants are performed in parallel (e.g., on a cluster of computers, with one mutant per node).

Step 2: Test case evolution, the procedure for generating new test cases is described as follows.

- 1: Select randomly whether to apply *mutation* or *crossover*
- 2: **if** Crossover is chosen **then**
- 3: Select 2 test cases (i, j) with probability $F(TC_i), F(TC_j)$

- 4: Apply crossover on TC_i and TC_j
- 5: **else**
- 6: Select a test case with probability of selection $F(TC_i)$
- 7: Apply mutation
- 8: **end if**
- 9: Add the new test cases to the new set of test cases

The basic mechanisms used to evolve a given test case are mutation and crossover. *Mutation* consists of a random change of the data used in the messages exchanged in a test case, similarly to the random generation described above. *Crossover* consists of the combination of two test cases. Two good test cases are chosen, some data in the second test case replace the data used in the first one.

The algorithm stops when the number of generation exceeds a given maximum number of generation. Otherwise, we go back to Step 1 and keep on testing continuously [5]. When no improvement of the fitness values is observed for a number of evolutionary iterations, Step 0 (Preparation) is repeated.

eCAT's performance and capability to reveal faults have been evaluated on two BDI agent case studies [8]. *eCAT* has been implemented as an Eclipse¹ plug-in. It supports testing agents implemented in JADE and JADEX, and the input ontology formats are those supported by Protégé² like OWL.

3. REFERENCES

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¹<http://www.eclipse.org>

²<http://protege.stanford.edu>